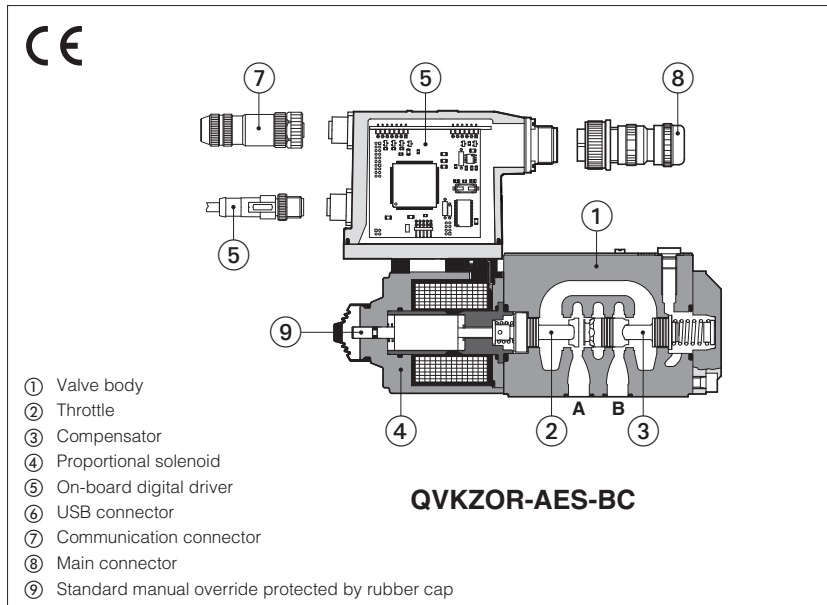


# Digital proportional flow valves

direct, pressure compensated, without transducer



## QVHZO-A, QVHZO-AEB, QVHZO-AES QVKZOR-A, QVKZOR-AEB, QVKZOR-AES

Proportional flow control valves, direct, pressure compensated without position transducer for open loop flow regulations.

**A** to be coupled with off-board drivers.

**AEB** basic execution, with on-board digital driver, analog reference signals and USB port for software functional parameters setting.

**AES** full execution, with on-board digital driver which includes also fieldbus interface for functional parameters setting, reference signals and real-time diagnostics.

### QVHZO:

Size: **06** - ISO 4401

Max flow: **45 l/min**

Max pressure: **210 bar**

### QVKZOR:

Size: **10** - ISO 4401

Max flow: **90 l/min**

Max pressure: **210 bar**

## 1 MODEL CODE

<b>QVKZOR</b>	-	<b>AES</b>	-	<b>BC</b>	-	<b>10</b>	/	<b>65</b>	/	*	/	*	/	*	/	*																
Pressure compensated flow control valves, direct <b>QVHZO</b> = size 06 <b>QVKZOR</b> = size 10																Series number	<b>Seals material</b> , see section 10: - = NBR <b>PE</b> = FKM <b>BT</b> = HNBR															
<p><b>A</b> = for off-board driver, see section 3  <b>AEB</b> = basic on-board digital driver (1)  <b>AES</b> = full on-board digital driver (2)</p> <p><b>Fieldbus interfaces</b>, USB port always present (3):  <b>NP</b> = Not present      <b>BP</b> = PROFIBUS DP  <b>BC</b> = CANopen          <b>EH</b> = EtherCAT</p> <p><b>Valve size ISO 4401:</b>    <b>0</b> = 06      <b>1</b> = 10</p> <p><b>Max regulated flow:</b></p> <table border="0"> <tr> <td>QVHZO:</td> <td></td> <td></td> <td>QVKZOR:</td> </tr> <tr> <td><b>3</b> = 3,5 l/min</td> <td><b>36</b> = 35 l/min</td> <td><b>65</b> = 65 l/min</td> <td></td> </tr> <tr> <td><b>12</b> = 12 l/min</td> <td><b>45</b> = 45 l/min</td> <td><b>90</b> = 90 l/min</td> <td></td> </tr> <tr> <td><b>18</b> = 18 l/min</td> <td></td> <td></td> <td></td> </tr> </table>																	QVHZO:			QVKZOR:	<b>3</b> = 3,5 l/min	<b>36</b> = 35 l/min	<b>65</b> = 65 l/min		<b>12</b> = 12 l/min	<b>45</b> = 45 l/min	<b>90</b> = 90 l/min		<b>18</b> = 18 l/min			
QVHZO:			QVKZOR:																													
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<b>18</b> = 18 l/min																																
<p><b>Coil voltage</b>, only for <b>A</b> - see section 16:                  - = standard coil for 24VDC Atos drivers  <b>6</b> = optional coil for 12VDC Atos drivers  <b>18</b> = optional coil for low current drivers</p> <p><b>Hydraulic options (4):</b>  <b>D</b> = quick venting of port B</p> <p><b>Hand lever options</b>, only for <b>QVHZO-A</b> - see section 13:  <b>MO</b> = horizontal hand lever  <b>MV</b> = vertical hand lever</p> <p><b>Electronics options</b>, only for <b>AEB</b> and <b>AES</b> (4):  <b>C</b> = current feedback for pressure transducer 4÷20 mA (omit for std voltage 0÷10 VDC) - only for <b>W</b>  <b>I</b> = current reference input 4÷20 mA (omit for std voltage ±10 VDC)  <b>Q</b> = enable signal  <b>Z</b> = double power supply, enable, fault and monitor signals -12 pin connector  <b>W</b> = power limitation function - 12 pin connector</p>																																

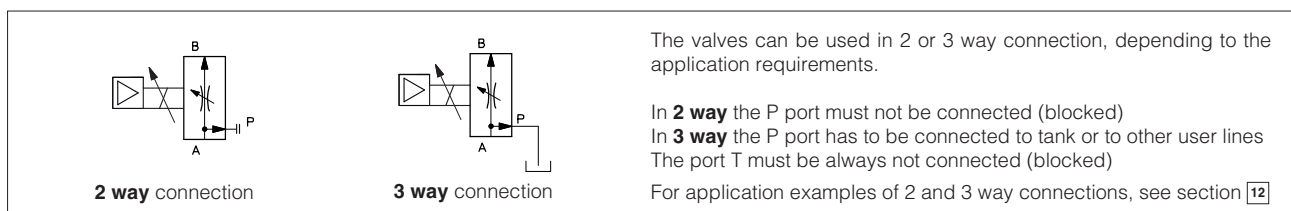
(1) Only for **NP**

(2) Only for **BC, BP, EH**

(3) Omit for **A** execution

(4) For possible combined options, see section 15

## 2 HYDRAULIC SYMBOLS



**Note:** hydraulic symbols are represented with on-board digital driver

### 3 OFF-BOARD ELECTRONIC DRIVERS - only for A

Drivers model	E-MI-AC-01F		E-MI-AS-IR		E-BM-AS-PS		E-BM-AES
Type	Analog				Digital		
Voltage supply (VDC)	12	24	12	24	12	24	24
Valve coil option	/6	std	/6	std	/6	std	std
Format	plug-in to solenoid				DIN-rail panel		
Tech table	G010		G020		G030		GS050

### 4 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FS900** and in the user manuals included in the E-SW-\* programming software.

### 5 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **FS900**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table **GS500**):

<b>E-SW-BASIC</b>	support: NP (USB)	PS (Serial)	IR (Infrared)
<b>E-SW-FIELDBUS</b>	support: BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
	EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
<b>E-SW-*/PQ</b>	support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)		

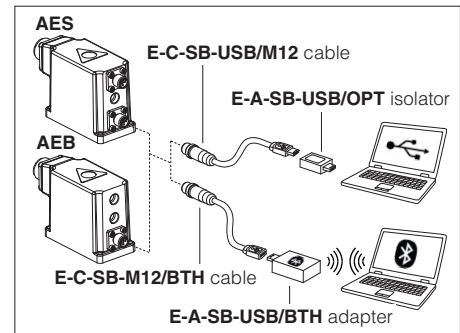


**WARNING: drivers USB port is not isolated!** For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection



**WARNING:** see tech table **GS500** for the list of countries where the Bluetooth adapter has been approved

#### USB or Bluetooth connection



### 6 FIELDBUS - only for AES, see tech. table **GS510**

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector.

### 7 GENERAL CHARACTERISTICS

Assembly position	Any position
Subplate surface finishing to ISO 4401	Acceptable roughness index: Ra ≤ 0,8, recommended Ra 0,4 – Flatness ratio 0,01/100
MTTFd valves according to EN ISO 13849	150 years, see technical table P007
Ambient temperature range	<b>A:</b> Standard = -20°C ÷ +70°C /PE option = -20°C ÷ +70°C /BT option = -40°C ÷ +60°C <b>AEB, AES:</b> Standard = -20°C ÷ +60°C /PE option = -20°C ÷ +60°C /BT option = -40°C ÷ +60°C
Storage temperature range	<b>A:</b> Standard = -20°C ÷ +80°C /PE option = -20°C ÷ +80°C /BT option = -40°C ÷ +70°C <b>AEB, AES:</b> Standard = -20°C ÷ +70°C /PE option = -20°C ÷ +70°C /BT option = -40°C ÷ +70°C
Surface protection	Zinc coating with black passivation, galvanic treatment (driver housing for AEB and AES)
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h
Compliance	CE according to EMC directive 2014/30/EU (Immunity: EN 61000-6-2; Emission: EN 61000-6-3) RoHS Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006

**8 HYDRAULIC CHARACTERISTICS** - based on mineral oil ISO VG 46 at 50 °C

Valve model	QVHZO					QVKZOR	
Max regulated flow [l/min]	3,5	12	18	35	45	65	90
Min regulated flow [cm <sup>3</sup> /min]	15	20	30	50	60	85	100
Regulating Δp [bar]	4 - 6		10 - 12		15	6 - 8	10 - 12
Max flow on port A [l/min]	40			50	55	70	100
Max pressure [bar]	210						
Response time 0-100% step signal [ms]	≤ 30					≤ 45	
Hysteresis	≤ 5 [% of the regulated max flow]						
Linearity	≤ 3 [% of the regulated max flow]						
Repeatability	≤ 1 [% of the regulated max flow]						

**Note:** above performance data refer to valves coupled with Atos electronic drivers, see section 3

**9 ELECTRICAL CHARACTERISTICS**

Power supplies	Nominal : +24 VDC Rectified and filtered : V <sub>RMS</sub> = 20 ÷ 32 V <sub>MAX</sub> (ripple max 10 % V <sub>PP</sub> )					
Max power consumption	QVHZO			QVKZOR		
	A = 30 W	AEB, AES = 50 W		A = 35 W	AEB, AES = 50 W	
Coil voltage code	standard	option /6	option /18	standard	option /6	option /18
Max. solenoid current	2,2 A	2,75 A	1,2 A	2,6 A	3,25 A	1,2 A
Coil resistance R at 20°C	3 ÷ 3,3 Ω	2 ÷ 2,2 Ω	13 ÷ 13,4 Ω	3,8 ÷ 4,1 Ω	2,2 ÷ 2,4 Ω	12 ÷ 12,5 Ω
Analog input signals	Voltage: range ±10 VDC (24 V <sub>MAX</sub> tollerant) Current: range ±20 mA			Input impedance: Ri > 50 kΩ Input impedance: Ri = 500 Ω		
Monitor output	Output range: voltage ±5 VDC @ max 5 mA					
Enable input	Range: 0 ÷ 9 VDC (OFF state), 15 ÷ 24 VDC (ON state), 9 ÷ 15 VDC (not accepted); Input impedance: Ri > 87 kΩ					
Fault output	Output range : 0 ÷ 24 VDC (ON state ≡ VL+ [logic power supply] ; OFF state ≡ 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)					
Pressure transducer power supply (only for /W option)	+24VDC @ max 100 mA (E-ATR-8 see tech table <b>GS465</b> )					
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, current control monitoring, power supplies level, pressure transducer failure (/W option)					
Insulation class	H (180°) Due to the occurring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account					
Protection degree to DIN EN60529	A = IP65; AEB, AES = IP66 / IP67 with mating connectors					
Duty factor	Continuous rating (ED=100%)					
Tropicalization	Tropical coating on electronics PCB					
Additional characteristics	Short circuit protection of solenoid's current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply					
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158		
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		
Recommended wiring cable	LiYCY shielded cables, see section 19					

**Note:** a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 V<sub>DC</sub> power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

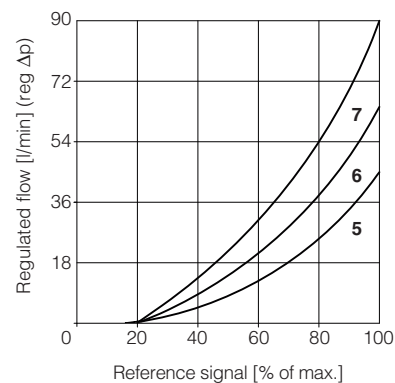
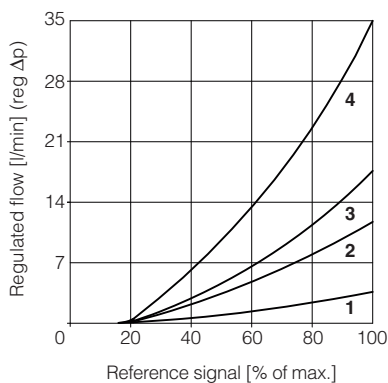
**10 SEALS AND HYDRAULIC FLUIDS** - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature	NBR seals (standard) = -20°C ÷ +60°C (+80°C for <b>A</b> ), with HFC hydraulic fluids = -20°C ÷ +50°C FKM seals (/PE option) = -20°C ÷ +80°C HNBR seals (/BT option) = -40°C ÷ +60°C, with HFC hydraulic fluids = -40°C ÷ +50°C		
Recommended viscosity	20 ÷ 100 mm <sup>2</sup> /s - max allowed range 15 ÷ 380 mm <sup>2</sup> /s		
Max fluid contamination level	normal operation	ISO4406 class 18/16/13 NAS1638 class 7	
	longer life	ISO4406 class 16/14/11 NAS1638 class 5	
		see also filter section at <a href="http://www.atos.com">www.atos.com</a> or KTF catalog	
<b>Hydraulic fluid</b>	<b>Suitable seals type</b>	<b>Classification</b>	<b>Ref. Standard</b>
Mineral oils	NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLDP	DIN 51524
Flame resistant without water	FKM	HFDU, HFDR	ISO 12922
Flame resistant with water	NBR, HNBR	HFC	

**11 DIAGRAMS** - based on mineral oil ISO VG 46 at 50 °C

**11.1 Regulation diagrams**

- 1 = QVHZO-\*-06/3
- 2 = QVHZO-\*-06/12
- 3 = QVHZO-\*-06/18
- 4 = QVHZO-\*-06/36
- 5 = QVHZO-\*-06/45
- 6 = QVKZOR-\*-10/65
- 7 = QVKZOR-\*-10/90

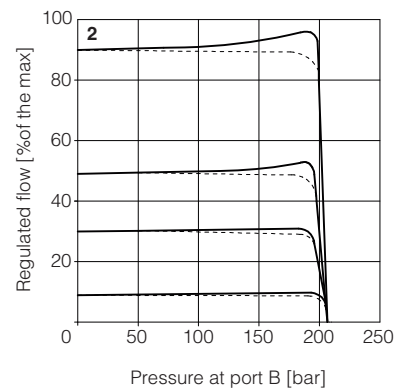
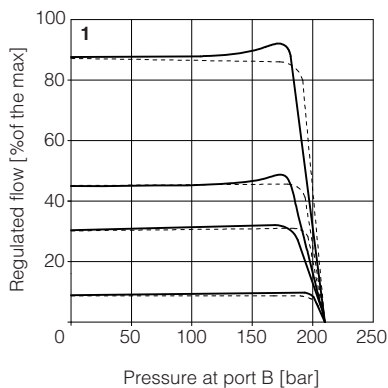


**11.2 Regulated flow/outlet pressure diagrams**

with inlet pressure = 210 bar

- 1 = QVHZO
- 2 = QVKZOR

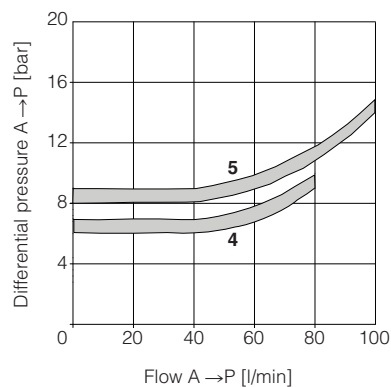
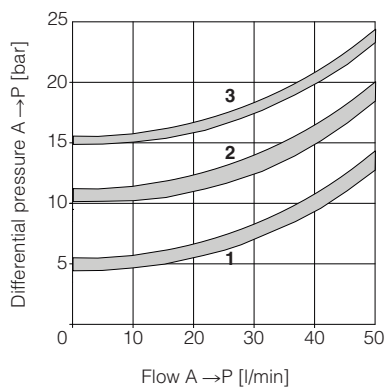
Dotted line for 3-way versions



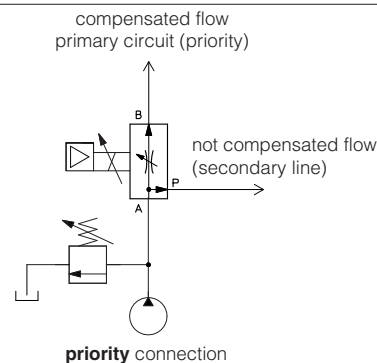
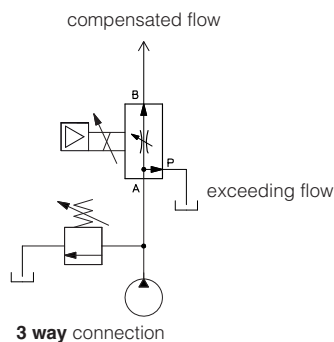
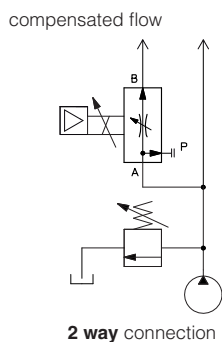
**11.3 Flow A → P/Δp diagrams**

3-way configuration

- 1 = QVHZO-\*-06/3
- 2 = QVHZO-\*-06/12
- 3 = QVHZO-\*-06/18
- 4 = QVHZO-\*-06/36
- 5 = QVHZO-\*-06/45
- 6 = QVKZOR-\*-10/65
- 7 = QVKZOR-\*-10/90



**12 APPLICATIONS AND CONNECTIONS**



**2 way connection**

The 2 way connection is normally used to control the flow in one part of the hydraulic circuit or to regulate the speed of a specific actuator. The metered flow in the controlled line is kept constant, independently to the load variations. If the valve is directly installed on the pump main line, the exceeding flow is returned to tank through the pressure relief valve.

**3 way connection**

The 3 way connection is normally used when the valve directly controls the pump flow (main line). The metered flow in the controlled line is kept constant, independently to the load variations. The exceeding flow (not metered by the valve) it is returned to tank through the valve P port = T line (3rd way).

**Priority connection**

The priority connection guarantees the pressure compensated flow supply to the primary circuit. The exceeding flow (not required by the primary circuit) is bypassed through the valve P port, to secondary circuit operating at lower pressure and not requiring compensated flow regulations.

### 13 HYDRAULIC OPTIONS

**D** = This option provides a quick venting of the use port B when the valve is closed or de-energized.

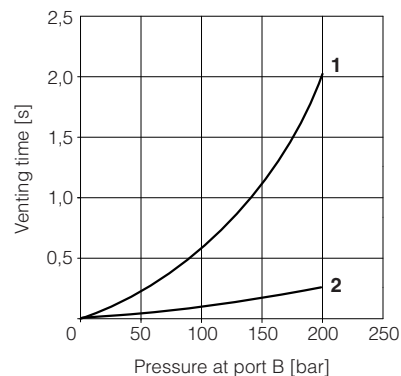
The valve must be connected in 3 way, with P port connected to tank.

When the proportional throttle is fully closed, the valve's port B is internally connected to port P (tank), permitting a quickly decompression of the pressure in the use line.

In the diagram aside are represented the venting times of **QVHZO** and **QVKZOR** with option /D respect to standard versions:

1 = standard version

2 = option /Q



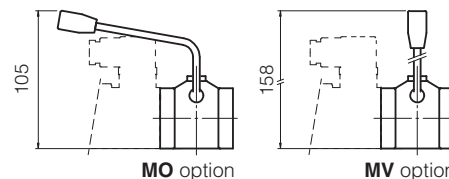
#### Hand lever option - only for **QVHZO-A**

It allows to operate the valve in absence of electrical power supply.

For detailed description of QVHZO-A with hand lever option see tech. table **E138**.

**MO** = Horizontal hand lever

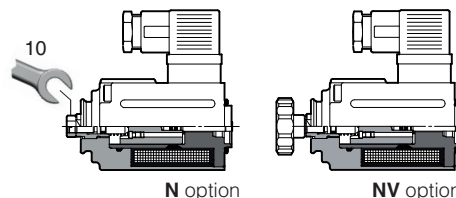
**MV** = Vertical hand lever



The following supplementary options allow to operate **QVHZO-A** and **QVKZOR-A** in absence of electrical power supply by means of a micrometric screw replacing the standard solenoid manual override, see tech. table **TK150**

**N** = Manual micrometric adjustment

**NV** = As option /N plus handwheel and graduated scale



### 14 ELECTRONICS OPTIONS - only for **AEB** and **AES**

**I** = This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard ±10 VDC.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

**Q** = This option permits to inhibit the valve function without removing the power supply to the driver. Upon disable command the current to the solenoid is zeroed and the valve's spool moves to rest position.

The option /Q is suggested for all cases where the valve has to be frequently inhibited during the machine cycle – see 17.5 for signal specifications.

**Z** = This option provides, on the 12 pin main connector, the following additional features:

**Fault output signal** - see 17.6

**Enable input signal** - see above option /Q

**Power supply for driver's logics and communication** - see 17.2

**C** = Only in combination with option /W

This option is available to connect pressure transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

**W** = Only for valves coupled with pressure compensator, see tech table **D150**.

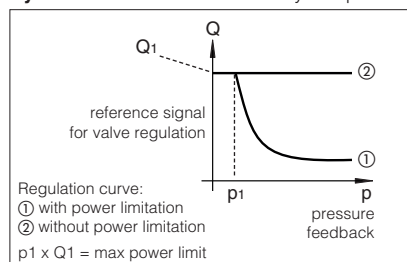
It provides the hydraulic power limitation function. The driver receives the flow reference signal by the analog input INPUT+ and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR.

When the actual requested hydraulic power  $p \times Q$  ( $TR \times INPUT+$ ) reaches the max power limit ( $p1 \times Q1$ ), internally set by software, the driver automatically reduces the flow regulation of the valve.

The higher is the pressure feedback the lower is the valve's regulated flow:

$$\text{Flow regulation} = \text{Min} \left( \frac{\text{PowerLimit [sw setting]}}{\text{Transducer Pressure [TR]}} ; \text{Flow Reference [INPUT+]} \right)$$

#### Hydraulic Power Limitation - only for option /W



### 15 POSSIBLE COMBINED OPTIONS

**Hydraulic options:** all combination possible

**Electronics options:** /IQ, /IZ, /IW, /CW, /CWI

## 16 COIL VOLTAGE OPTIONS - only for A

6 = Optional coil to be used with Atos drivers with power supply 12 V<sub>DC</sub>.


18 = Optional coil to be used with electronic drivers not supplied by Atos.

## 17 POWER SUPPLY AND SIGNALS SPECIFICATIONS - only for AEB and AES

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

### 17.1 Power supply (V+ and V0)


The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers. In case of separate power supply see 17.2.

 A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

### 17.2 Power supply for driver's logic and communication (VL+ and VL0) - only for /Z and /W options

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 9 and 10, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

 A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

### 17.3 Reference input signal (INPUT+)

The driver controls in closed loop the current to the valve proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are 0 ÷ 10 V<sub>DC</sub> for standard and 4 ÷ 20 mA for /I option.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 V<sub>DC</sub> or ± 20 mA.

Drivers with fieldbus interface (BC, BP, EH) can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 ÷ 24V<sub>DC</sub>.

### 17.4 Monitor output signals (MONITOR and MONITOR2)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is 0 ÷ 5 V<sub>DC</sub> (1V = 1A).

Output signal can be reconfigured via software, within a maximum range of ±5 V<sub>DC</sub>.

#### Option /W

The driver generates a second analog output signal (MONITOR2) proportional to the actual system pressure.

The output maximum range is ±5 V<sub>DC</sub>; default setting is 0 ÷ 5 V<sub>DC</sub>.

### 17.5 Enable input signal (ENABLE) - not for standard

To enable the driver, supply a 24 V<sub>DC</sub> on pin 3 (pin C): Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849.

Enable input signal can be used as generic digital input by software selection.

### 17.6 Fault output signal (FAULT) - only for /Z and /W options

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal broken for 4 ÷ 20 mA input, etc.).

Fault presence corresponds to 0 V<sub>DC</sub>; normal working corresponds to 24 V<sub>DC</sub>.

Fault status is not affected by the Enable input signal.

### 17.7 Remote pressure transducer input signal (TR+) - only for /W option

Analog pressure transducers can be directly connected to the driver (see 18.4).

Analog input signal is factory preset according to selected driver code, defaults are 0 ÷ 10 V<sub>DC</sub> for standard and 4 ÷ 20 mA for /C option.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 V<sub>DC</sub> or ± 20 mA.

Note: transducer feedback can be read as a digital information through fieldbus communication - software selectable.

## 18 ELECTRONIC CONNECTIONS

### 18.1 Main connector signals - 7 pin (A1) Standard and /Q option - for AEB and AES

PIN	Standard	/Q	TECHNICAL SPECIFICATIONS	NOTES
A	V+		Power supply 24 Vdc	Input - power supply
B	V0		Power supply 0 Vdc	Gnd - power supply
C	AGND		Analog ground	Gnd - analog signal
		ENABLE	Enable (24 Vdc) or disable (0 Vdc) the driver, referred to V0	Input - on/off signal
D	INPUT+		Reference input signal: $\pm 10$ Vdc / $\pm 20$ mA maximum range Defaults are 0 $\div$ 10 Vdc for standard and 4 $\div$ 20 mA for /I option	Input - analog signal <b>Software selectable</b>
E	INPUT-		Negative reference input signal for INPUT+	Input - analog signal
F	MONITOR referred to: AGND	V0	Monitor output signal: $\pm 5$ Vdc maximum range Default is 0 $\div$ 5 Vdc (1V = 1A)	Output - analog signal <b>Software selectable</b>
G	EARTH		Internally connected to driver housing	

### 18.2 Main connector signals - 12 pin (A2) /Z and /W options - for AEB and AES

PIN	/Z	/W	TECHNICAL SPECIFICATIONS	NOTES
1	V+		Power supply 24 Vdc	Input - power supply
2	V0		Power supply 0 Vdc	Gnd - power supply
3	ENABLE		Enable (24 Vdc) or disable (0 Vdc) the driver, referred to VLO	Input - on/off signal
4	INPUT+		Reference input signal: $\pm 10$ Vdc / $\pm 20$ mA maximum range Defaults are 0 $\div$ 10 Vdc for standard and 4 $\div$ 20 mA for /I option	Input - analog signal <b>Software selectable</b>
5	INPUT-		Negative reference input signal for INPUT+	Input - analog signal
6	MONITOR		Monitor output signal: $\pm 5$ Vdc maximum range, referred to VLO Default is 0 $\div$ 5 Vdc (1V = 1A)	Output - analog signal <b>Software selectable</b>
7	NC		Do not connect	
8	NC		Do not connect	
		MONITOR2	2nd monitor output signal: $\pm 5$ Vdc maximum range, referred to VLO. Default is 0 $\div$ 5 Vdc	Output - analog signal
9	VL+		Power supply 24 Vdc for driver's logic and communication	Input - power supply
10	VLO		Power supply 0 Vdc for driver's logic and communication	Gnd - power supply
11	FAULT		Fault (0 Vdc) or normal working (24 Vdc), referred to VLO	Output - on/off signal
PE	EARTH		Internally connected to driver housing	

**Note:** do not disconnect VLO before VL+ when the driver is connected to PC USB port

### 18.3 Communication connectors - for AEB (B) and AES (B) - (C)

(B) USB connector - M12 - 5 pin always present		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V_USB	Power supply
2	ID	Identification
3	GND_USB	Signal zero data line
4	D-	Data line -
5	D+	Data line +

(C1) BC fieldbus execution, connector - M12 - 5 pin (2)		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	CAN_SHLD	Shield
2	NC	do not connect
3	CAN_GND	Signal zero data line
4	CAN_H	Bus line (high)
5	CAN_L	Bus line (low)

(C2) BP fieldbus execution, connector - M12 - 5 pin (2)		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V	Termination supply signal
2	LINE-A	Bus line (high)
3	DGND	Data line and termination signal zero
4	LINE-B	Bus line (low)
5	SHIELD	

(C3) (C4) EH fieldbus execution, connector - M12 - 4 pin (2)		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
Housing	SHIELD	

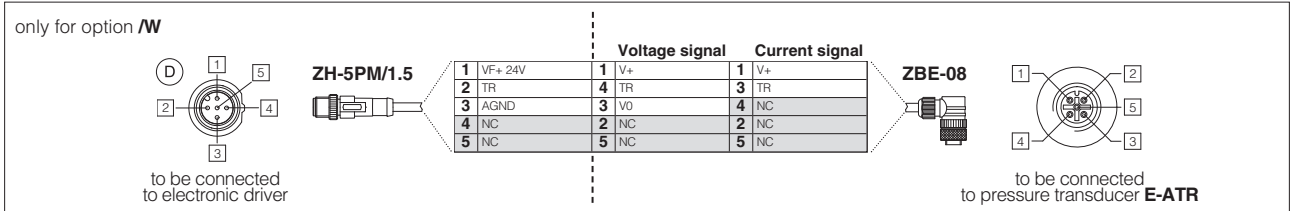
(1) Shield connection on connector's housing is recommended

(2) Only for AES execution

**18.4 Remote pressure transducer connector - M12 - 5 pin - only for /W option - for AEB and AES (D)**

PIN	SIGNAL	TECHNICAL SPECIFICATION	Voltage	Current
1	<b>VF +24V</b>	Power supply +24Vdc	Connect	Connect
2	<b>TR</b>	Signal transducer maximum range $\pm 10$ Vdc / $\pm 20$ mA, software selectable Defaults are $0 \div 10$ Vdc for standard and $4 \div 20$ mA for /C option	Connect	Connect
3	<b>AGND</b>	Common GND for transducer power and signals	Connect	/
4	<b>NC</b>	Not Connect	/	/
5	<b>NC</b>	Not Connect	/	/

**Remote pressure transducer connection - example**

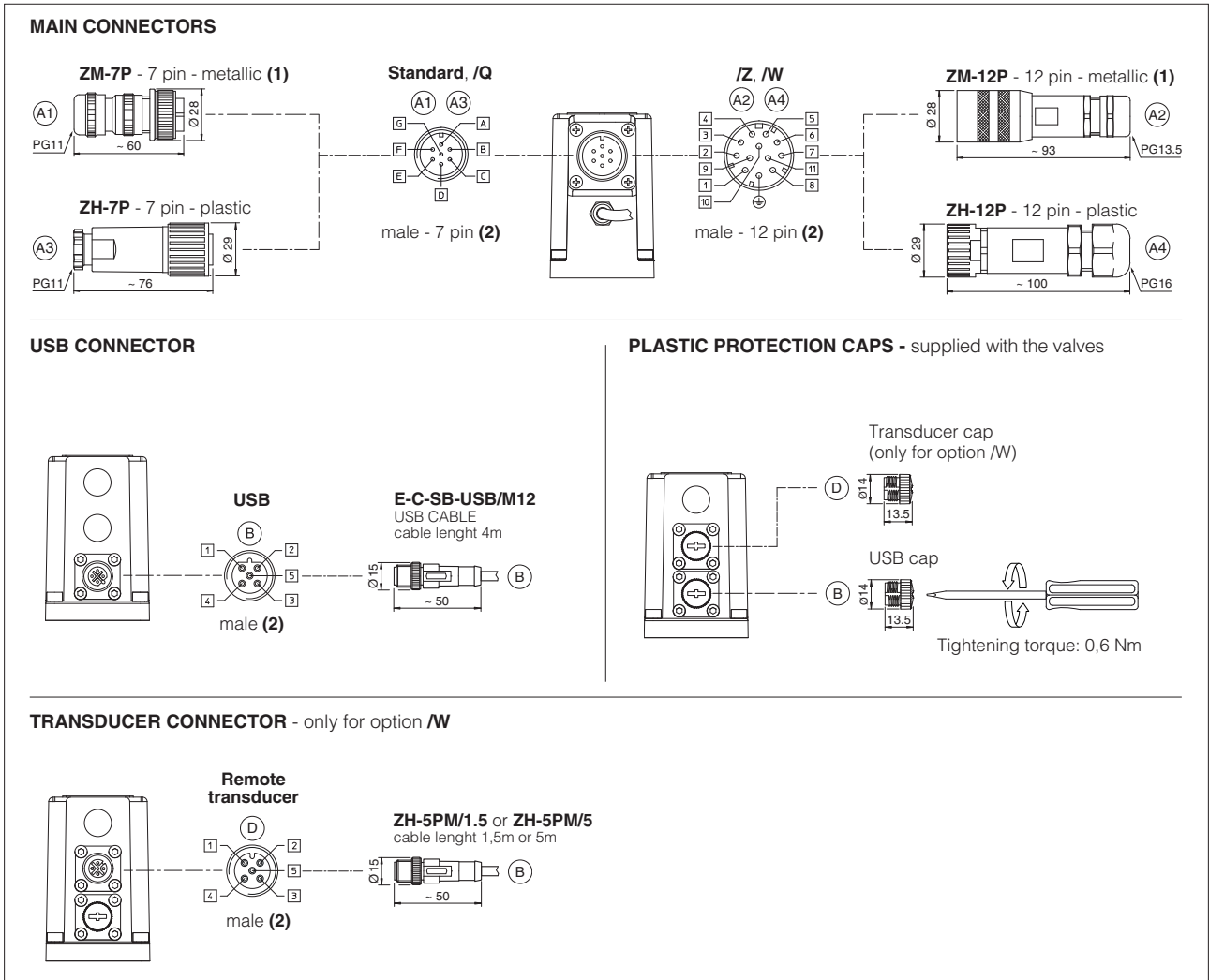


**Note:** connectors front view

**18.5 Solenoid connection - only for A**

PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 666
1	<b>COIL</b>	Power supply	
2	<b>COIL</b>	Power supply	
3	<b>GND</b>	Ground	

**18.6 AEB connections layout**



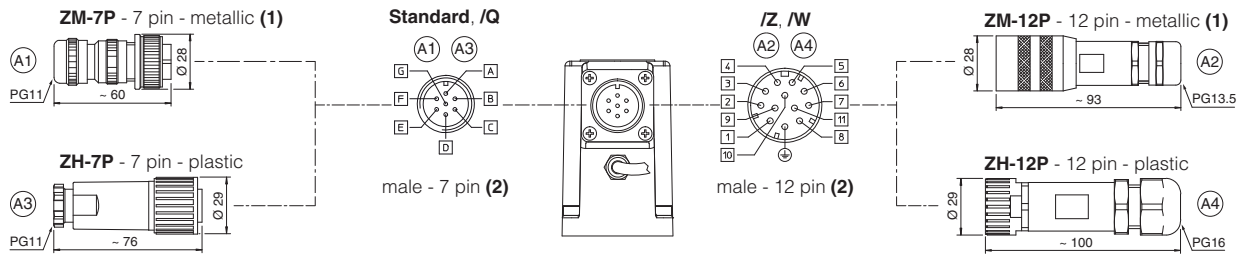
**(1)** Use of metallic connectors is strongly recommended in order to fulfill EMC requirements

**(2)** Pin layout always referred to driver's view

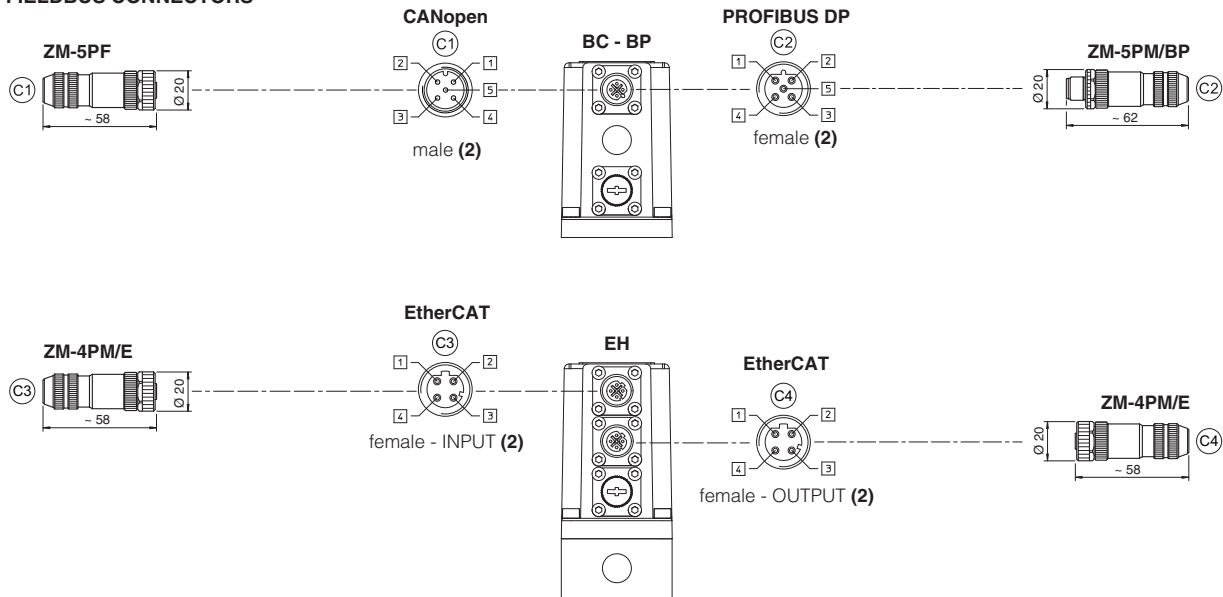


## 18.7 AES connections layout

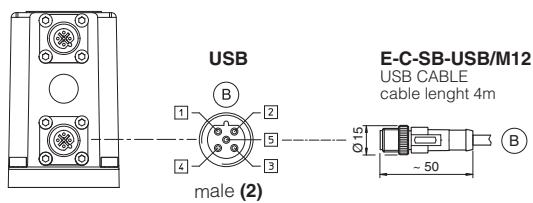
### MAIN CONNECTORS



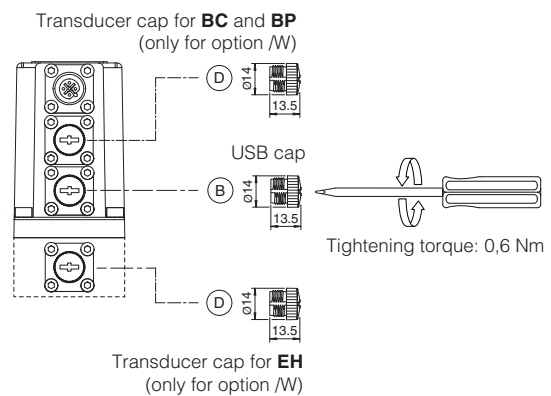
### FIELDBUS CONNECTORS



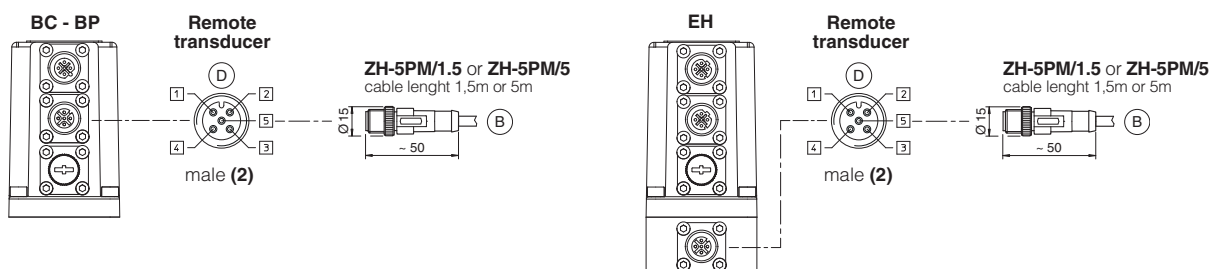
### USB CONNECTOR



### PLASTIC PROTECTION CAPS - supplied with the valves



### TRANSDUCER CONNECTOR - only for option /W



(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements

(2) Pin layout always referred to driver's view

**19 CONNECTORS CHARACTERISTICS** - to be ordered separately

**19.1 Main connectors - 7 pin - for AEB and AES**

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY
<b>CODE</b>	<b>(A1) ZM-7P</b>	<b>(A3) ZH-7P</b>
Type	7pin female straight circular	7pin female straight circular
Standard	According to MIL-C-5015	According to MIL-C-5015
Material	Metallic	Plastic reinforced with fiber glass
Cable gland	PG11	PG11
Recommended cable	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)
Conductor size	up to 1 mm <sup>2</sup> - available for 7 wires	up to 1 mm <sup>2</sup> - available for 7 wires
Connection type	to solder	to solder
Protection (EN 60529)	IP 67	IP 67

**19.2 Main connectors - 12 pin - for AEB and AES**

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY
<b>CODE</b>	<b>(A2) ZM-12P</b>	<b>(A4) ZH-12P</b>
Type	12pin female straight circular	12pin female straight circular
Standard	DIN 43651	DIN 43651
Material	Metallic	Plastic reinforced with fiber glass
Cable gland	PG13,5	PG16
Recommended cable	LiYCY 12 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply)	LiYCY 10 x 0,14mm <sup>2</sup> max 40 m (logic) LiYY 3 x 1mm <sup>2</sup> max 40 m (power supply)
Conductor size	0,5 mm <sup>2</sup> to 1,5 mm <sup>2</sup> - available for 12 wires	0,14 mm <sup>2</sup> to 0,5 mm <sup>2</sup> - available for 9 wires 0,5 mm <sup>2</sup> to 1,5 mm <sup>2</sup> - available for 3 wires
Connection type	to crimp	to crimp
Protection (EN 60529)	IP 67	IP 67

**19.3 Fieldbus communication connectors - only for AES**

CONNECTOR TYPE	BC CANopen (1)		BP PROFIBUS DP (1)		EH EtherCAT (2)
<b>CODE</b>	<b>(C1) ZM-5PF</b>	<b>(C2) ZM-5PM</b>	<b>(C1) ZM-5PF/BP</b>	<b>(C2) ZM-5PM/BP</b>	<b>(C1) (C2) ZM-4PM/E</b>
Type	5 pin female straight circular	5 pin male straight circular	5 pin female straight circular	5 pin male straight circular	4 pin male straight circular
Standard	M12 coding A – IEC 61076-2-101		M12 coding B – IEC 61076-2-101		M12 coding D – IEC 61076-2-101
Material	Metallic		Metallic		Metallic
Cable gland	Pressure nut - cable diameter 6÷8 mm		Pressure nut - cable diameter 6÷8 mm		Pressure nut - cable diameter 4÷8 mm
Cable	CANbus Standard (DR 303-1)		PROFIBUS DP Standard		Ethernet standard CAT-5
Connection type	screw terminal		screw terminal		terminal block
Protection (EN 60529)	IP67		IP 67		IP 67



**(1)** E-TRM-\*\* terminators can be ordered separately - see tech table **GS500**

**(2)** Internally terminated

**19.4 Pressure transducer connectors - only for /W option**

CONNECTOR TYPE	TRANSDUCER	
<b>CODE</b>	<b>(D1) ZH-5PM/1.5</b>	<b>(D1) ZH-5PM/5</b>
Type	5 pin male straight circular	
Standard	M12 coding A – IEC 61076-2-101	
Material	Plastic	
Cable gland	Connector moulded on cables	
	1,5 m lenght	5 m lenght
Cable	5 x 0,25 mm <sup>2</sup>	
Connection type	molded cable	
Protection (EN 60529)	IP 67	

**20 FASTENING BOLTS AND SEALS**

	QVHZO	QVKZOR
	<p><b>Fastening bolts:</b> 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm</p>	<p><b>Fastening bolts:</b> 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm</p>
	<p><b>Seals:</b> 4 OR 108 Diameter of ports A, B, P, T: Ø 7,5 mm</p>	<p><b>Seals:</b> 5 OR 2050 Diameter of ports A, B, P, T: Ø 11,2 mm</p>

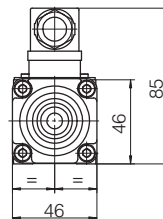
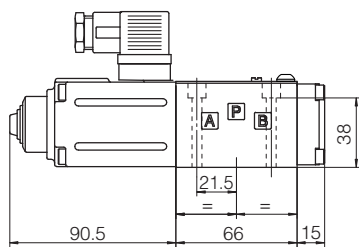
21 INSTALLATION DIMENSIONS FOR QVHZO [mm]

ISO 4401: 2005

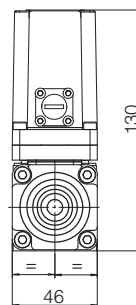
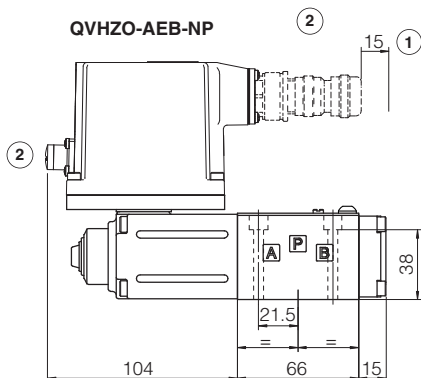
Mounting surface: 4401-03-02-0-05 (see tab. P005)

Mass [kg]		
A	AEB, AES	AES-EH
2,3	2,8	2,9

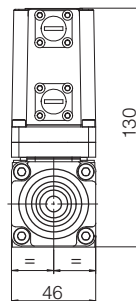
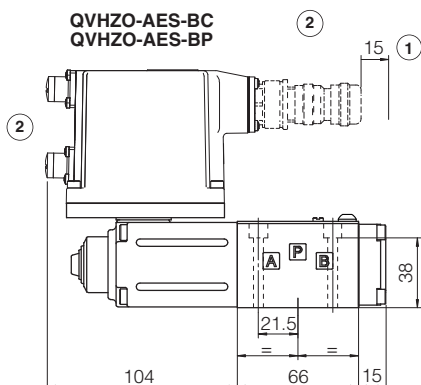
QVHZO-A



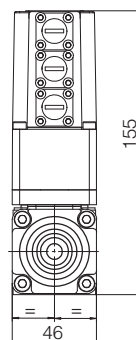
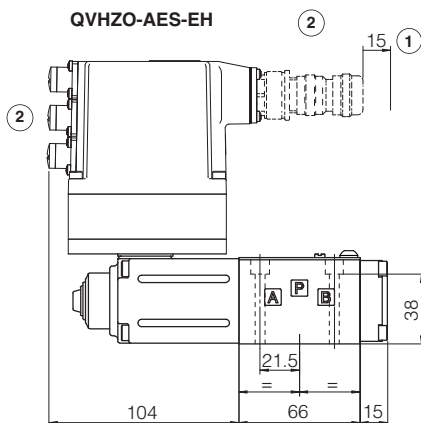
QVHZO-AEB-NP



QVHZO-AES-BC  
QVHZO-AES-BP



QVHZO-AES-EH



① = Space to remove the connectors

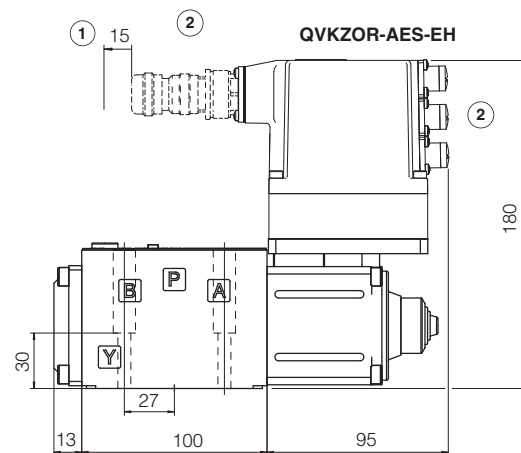
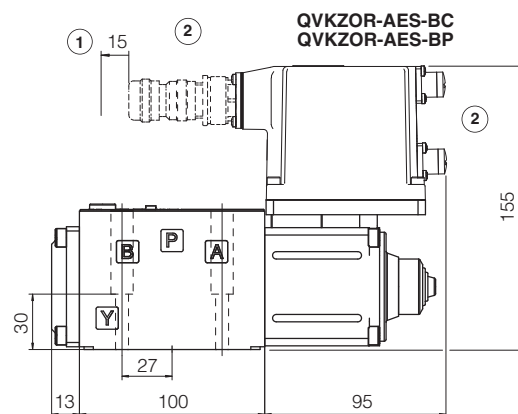
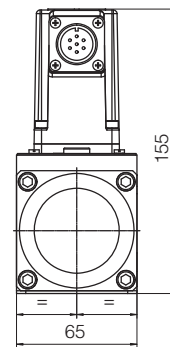
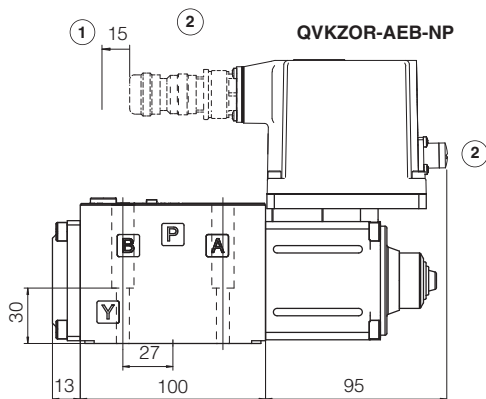
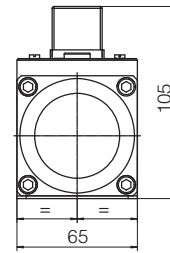
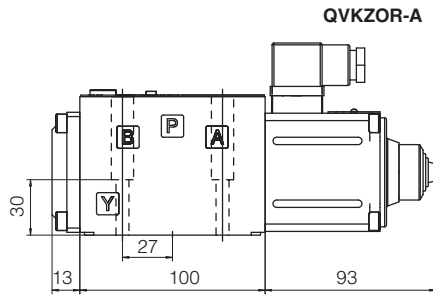
② = The dimensions of all connectors must be considered, see section 18.6 and 18.7

## 22 INSTALLATION DIMENSIONS FOR QVHZOR [mm]

ISO 4401: 2005

Mounting surface: 4401-05-04-0-05 (see tab. P005)

Mass [kg]		
A	AEB, AES	AES-EH
3,8	4,3	4,4



① = Space to remove the connectors

② = The dimensions of all connectors must be considered, see section 18.6 and 18.7

## 23 RELATED DOCUMENTATION

**FS001** Basics for digital electrohydraulics  
**FS900** Operating and maintenance information for proportional valves  
**G010** E-MI-AC analog driver  
**G020** E-MI-AS-IR digital driver  
**G030** E-BM-AS digital driver  
**GS050** E-BM-AES digital driver  
**GS500** Programming tools

**GS510** Fieldbus  
**K800** Electric and electronic connectors  
**P005** Mounting surfaces for electrohydraulic valves  
**QB200** Quickstart for AEB valves commissioning  
**QF200** Quickstart for AES valves commissioning